ULTRASONIC WAVE PROPAGATION AND ATTENUATION IN WET BONE

Roderic Lakes, Hyo Sub Yoon and J. Lawrence Katz

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ABSTRACT

The propagation of ultrasonic longitudinal waves in bovine plexiform and human Haversian bone has been studied over the range 0.5-16 MHz. In wet bone little velocity dispersion was observed, in contrast to the results of earlier studies on dry bone. Large values of attenuation were observed.

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Keywords: Bone; ultrasonics

INTRODUCTION

Ultrasonic studies of bone and other calcified tissues are motivated principally by two considerations: achieving a greater understanding of the role of microstructure in determining the mechanical properties of the tissue, and developing clinical diagnostic tools for the assessment of disease states. Among basic studies are the experiments by Yoon and Katz 1,2 and Lang 3 in which the texture symmetry and the full set of anisotropic elastic constants were determined. Human Haversian bone behaves as a quasihexagonal or axisymmetric material with five independent elastic constants 2,3. Bovine plexiform bone behaves as an orthotropic material with nine independent elastic constants⁴. Recently it has been suggested that human bone is also orthotropic in its mechanical properties, albeit the deviations from hexagonal symmetry are small.

In the clinical domain, efforts have been made to use ultrasound to diagnose a variety of skeletal disorders. For example, changes in the waveforms of propagated ultrasonic waves have been related to the degree of healing of fractures by Brown and Mavor⁶. A device based on detection of the magnetic field produced by ultrasonic waves in bone via the piezoelectric effect was developed by Lakes and Saha⁷ to avoid artifacts due to soft tissue properties. Acoustic emission methods were used by Yoon et al.8 to explore effects associated with surgical defects and microdamage in bone under

It is the purpose of this investigation to examine the dispersion and attenuation of ultrasonic waves in bone to provide an insight into structure-related micromechanical processes and characteristics of bone tissue, and to understand how simulated acoustic emission signals are propagated in bone in

Department of Biomedical Engineering, Rensselaer Polytechic Institute, Trov. NY 12181, USA

Reprints from Professor R. Lakes, Department of Biomedical Engineering, The University of Iowa, Iowa City, IA 52242, USA the clinical application of acoustic emission techniques.

EXPERIMENTAL METHODS

Specimen preparation

Fresh-frozen femoral compact bone from cows, and femoral compact bone from a human cadaver were used for this investigation. Bovine specimen B₁ was taken from the lateral aspect of the midshaft of a femur. Human bone specimens were cut from the lateral aspect of the femoral midshaft from a female subject aged 56 years. Specimens H_{1a}, H_{1b}, H_{2a}, H_{2b} were from adjacent areas of this bone. Specimens were cut while wet, into rectangular parallelepipeds with an Isomet low-speed diamond saw (Buehler Ltd., Lake Bluff, IL). The specimen axes were aligned with the microstructural symmetry axes of the bone tissue. Specimens were frozen when not under study and were kept wet in Ringer's solution with penicillin and streptomycin between experiments. Specimen dimensions were as shown in Table 1.

The surface of each specimen was ground and polished using the usual metallographic techniques, all were mounted on an alignment device with double sided adhesive tape and ground with graded abrasives on a strip grinder (Handimet, Buehler Ltd.). The structural orientation was then checked by reflected light microscopy.

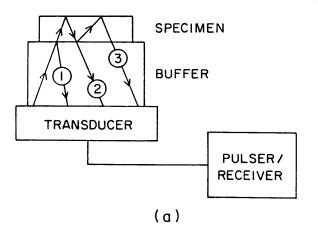
Table 1 Dimensions of samples

	Length (mm:	Circumferential length (mm)	Radial length (mm)
Bovine B ₁	15.82	9.45	6.65
Human H _{ia}	10.41	5.64	3.21
Human H _{1b}	5.86	5.64	3.21
Human H,	10.84	4.06	1.78
Human H	10.84	2.21	1.78

Ultrasonic measurements

In this study, electrical pulses were generated by a Matec (Warwick, RI) 6600 pulser/receiver, or by an Arenberg (Jamaica Plain, MA) pulser. The electrical pulses were fed into a broadband piezoelectric transducer (Panametrics, Waltham, MA). Transducers of resonant frequency 1.0, 2.25, 5.0 and 10.0 MHz were used to generate longitudinal waves in the specimen and experiments were conducted at room temperature (23.5 \pm 0.5°C), with water as a couplant.

Three kinds of ultrasonic velocity measurements were made. First, wave packets containing from seven to ten oscillations were generated and the transmission delay of the peak of the pulse envelope through the specimen was measured on an oscilloscope (Tektronix type 465 with digital



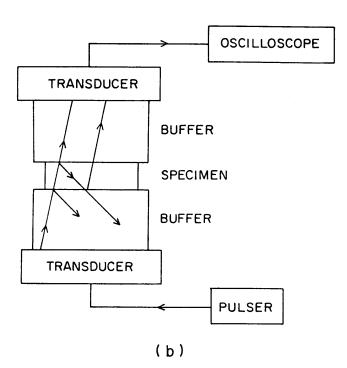


Figure 1 Configuration of transducers for ultrasonic measurements. a, Single transducer arrangement for pulse echo measurements. b, Two transducer system for echo and transmission measurements. Paths of the various reflected waves are indicated schematically by arrows

time delay indicator). The group velocity was then calculated by dividing the specimen thickness by the time delay. Second, long wave packets containing many oscillations were used and time delay measured from the leading edge of the waveform. The first oscillation in the leading edge which exceeded one third the maximum amplitude, was identified and the zero crossing following that peak used to determine the signal time delay. The signal velocity was then calculated from the delay. Third, phase velocities were determined using a pulse echo overlap method. In this method, pairs of echoes are compared by driving the horizontal input of an oscilloscope at a frequency equal to the reciprocal of the travel time between the echoes 9-11. The method outlined by Papadakis¹⁰ was applied to achieve a proper cycle for cycle match between the two echoes, to obtain the phase delay, and hence also the phase velocity. In this investigation a buffer rod of polymethyl methacrylate (PMMA) was used, as shown in Figure 1a. The buffer served to delay the echoes so they would not be masked by ringing from the drive pulse. The buffer rod diameter was sufficiently large (50 mm) in relation to its thickness (25 mm) to ensure that echoes from its cylindrical boundary did not obtrude into the received signal.

The pulse echo overlap method was also used to collect measurements of attenuation in bone. Again the buffer configuration shown in Figure 1 a was used. By contrast, in the original versions of this method 9,10 a quartz transducer was bonded directly to the specimen. Such an approach would not be satisfactory for experiments upon bone for the following reasons. Bone specimens can only be obtained in relatively small sizes if measurements in the radial and circumferential directions are to be made; as a consequence, short wave packets with negligible ringing must be used. Broadband transducers with large coupling coefficients and significant internal damping were used in this study. In contrast to the bonded quartz transducers described by Papadakis10, our transducers, by virtue of the absorption of acoustic energy, would introduce unacceptable attenuation errors if bonded to the specimen. To minimize these problems a buffer rod was used11.

Attenuation was calculated as follows. Following Papadakis 11 the attenuation α is given by

$$\alpha = \left[\ln(-R/(A_3/A_2))\right]/2t$$

in which t is the specimen thickness, R is the reflection coefficient for the buffer-specimen interface, and A_1 , A_2 and A_3 are the (signed) amplitudes of subsequent echoes. The first echo amplitude A_1 can be used to calculate R, but does not explictly appear in the equation for α . Since the specimen was smaller than the end of the buffer rod, the first echo contained reflections from a specimen-buffer and an air-buffer interface. Therefore, the method of Papadakis¹¹ for calculating R from the echo amplitudes could not

be used. Instead, R was calculated from the acoustic impedances of the specimen Z_S and buffer, Z_{R} :

$$R = \frac{Z_{\rm B} - Z_{\rm S}}{Z_{\rm B} + Z_{\rm S}}$$

The acoustic impedances, given by $Z = \rho V$, were calculated from the density ρ and wave velocity V of each material.

Errors in the calculated attenuation depend on errors in the measured echo amplitudes and reflection coefficient. Errors are minimized when the reflection coefficient is between 0.4 and 0.6, as was the case in this study. Estimated errors in the results are 10–15% in the attenuations and 1% in the velocities.

It was not possible to measure attenuations over the full frequency range 1–16 MHz using the pulse echo method, due to the large values of attenuation observed at the higher frequencies. Specifically, it was necessary in this method to observe two subsequent echoes to determine the attenuation. The second echo, after traversing a distance equal to four times the specimen thickness, became excessively attenuated at frequencies above 6 MHz. The transmission configuration of Figure 1b was therefore used to infer attenuations at higher frequencies; in this configuration the wave packet need only traverse the specimen once. The attenuation at a frequency ν_1 is given by

$$\alpha(\nu_1) = \alpha(\nu_0) + \frac{1}{t} \ln [T(\nu_0)/T(\nu_1)]$$

in which t is the specimen thickness, $T(\nu_0)$ is the transmission coefficient of the specimen at frequency ν_0 and $T(\nu_1)$ is the transmission coefficient at frequency ν_1 . $\alpha(\nu_0)$ is the absolute attenuation at frequency ν_0 (here 5 MHz) as determined by the pulse echo method. The

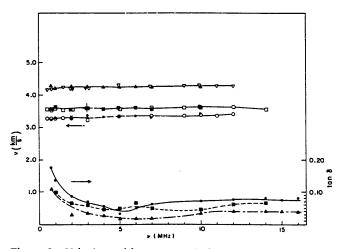


Figure 2 Velocity and loss tangent in bovine bone. Group velocity; loss tangent: ▲, longitudinal direction; ■, circumferential direction; ●, radial direction. Signal velocity: ∇, longitudinal direction; □, circumferential direction; ○, radial direction. Phase velocity: ▼, longitudinal direction;

+, circumferential direction; x, radial direction

acoustic impedance mismatch between specimen and buffer does not appear in this expression since it was assumed to be independent of frequency, an assumption considered justified in view of the smallness of the velocity dispersion in bone and PMMA.

The loss tangent was calculated from the attenuation α to facilitate comparison with the results of viscoelastic measurements obtained elsewhere under quasistatic sinusoidal loading. The loss tangent tan δ is given by 12

$$\tan \frac{\delta}{2} = \frac{\alpha v}{2\pi \nu}$$

in which v is the wave velocity and v is the frequency.

RESULTS

The group velocity, phase velocity, signal velocity and loss tangent of longitudinal waves in bovine bone are plotted in *Figure 2*. The signal velocity and loss tangent for human bone are shown in *Figure 3* and the attenuation for both bovine and human bone in *Figure 4*.

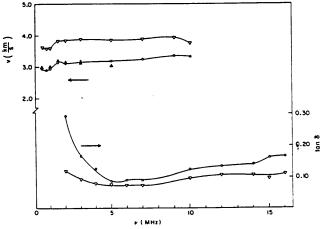


Figure 3 Signal velocity and loss tangent in human bone. ∇ , longitudinal direction; \triangle , circumferential direction; \bigcirc , radial direction

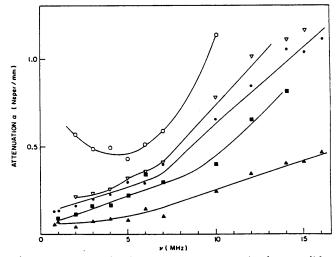


Figure 4 Attenuation in nepers per mm. Bovine bone, solid symbols as in Figure 2. Human bone, open symbols

In wet bovine bone, there was essentially no dispersion of velocity. In a nondispersive medium, the phase, group and signal velocities should be identical and as will be seen from Figure 2 these velocities do indeed coincide. Human bone exhibited some dispersion at the lower frequencies (Figure 3). Our results contrast with dispersion measurements performed on dry bone, in which for longitudinal waves propagating along the bone axis, the signal velocity dispersion was 2.9% and perpendicular to the bone axis it was 10.7% over the frequency range 2–10 MHz¹³. Sound velocity in dry bone was found to depend linearly on frequency¹³.

In the course of this study, a new kind of longitudinal wave was observed, which travelled more slowly than was expected. This wave was not foreseen in the design of the experiments; the interested reader is referred to a previously published report¹⁴.

DISCUSSION

In a material of biological origin, variations in physical properties may be expected to occur as a result of differences in structure and composition. It is therefore not surprising that in a larger group of specimens of wet bone, dispersion has recently been observed in some specimens⁴. Nevertheless, these dispersion values are considerably less than those from dry bone. Our results and those of Reference 4 support the conclusion that wet bone is less dispersive than dry bone. In the human bone examined in this study, the dispersion exhibited at the lower frequencies is attributed to a geometrical cause: the transition from extensional to longitudinal wave motion. The corresponding transition in the bovine bone would be below the lowest frequency used here, due to the larger size of that specimen.

The attenuation results obtained in this study may be compared with those of other investigators. Few studies of wave attenuation in compact bone have been reported. Adler and Cook 15 measured the attenuation of longitudinal waves in wet canine (Haversian) tibial bone at 22°C: 13 dB/cm at 3 MHz and 19 dB/cm at 5 MHz, values which are equivalent to 0.14 nepers/mm and 0.22 nepers/mm, respectively. They lie between the values obtained by us for human bone (0.23 nepers/mm at 5 MHz) and bovine bone (0.067 nepers/mm) in the longitudinal direction. Attenuation in bone significantly exceeds that in polymethyl methacrylate 16 (PMMA), 0.018 nepers/mm at 1 MHz and 21.1°C, but it is comparable with values obtained in composites, e.g., 0.26 nepers/mm at 2 MHz in a random particulate composite¹⁷, and 0.14 nepers/mm at 2.75 MHz in a fibrous composite 18.

Expressed in terms of the loss tangent, our attenuation results may be compared with

viscoelastic measurements on bone at lower frequencies. Specifically, the loss tangent of human and bovine bone is approximately 0.01 in torsion between 1 and 100 Hz ¹⁹ and is 0.01 and 0.02 in bending between 100 Hz and 1 kHz²⁰. The loss tangents determined from our measurements at ultrasonic frequencies are by contrast significantly larger, by a factor of up to thirty. It may therefore be of interest to examine some of the loss mechanisms which can act at ultrasonic frequencies.

Attenuation mechanisms in bone may be considered in relation to its microstructure, however definitive identification of mechanisms is rendered difficult by the complexity of the bony microstructure. Specifically, bone may be regarded as a composite with particulate, porous and fibrous structural elements at different levels of scale; the nature and typical size of these structural elements are shown in *Table 2*. The microstructure of human compact bone is shown in *Figure 5* and the microstructure of bovine plexiform bone in Reference 14. In the sequel, we discuss hypothetical wave attenuation mechanisms in bone in the context of results for simpler materials.

Scattering of waves from inhomogeneities has been identified as an attenuation mechanism in various synthetic composites 17,21. In composites with a regular periodic structure, a sharp maximum in the attenuation is expected when the ultrasonic wavelength equals twice the size of the unit cell in the propagation direction 18. This condition corresponds to a cut-off frequency at which the wavespeed drops to zero. Such frequencies, calculated for bone, are displayed in Table 2. Experimental evidence for the above mentioned phenomena has been found in composites with regular periodic microstructures 18, but not in those with random microstructures 17. We found no evidence of a cut-off frequency; its absence in bone may be attributed to aperiodicity in the microstructure of bone, and/or stiffening of the cement substance between osteons or laminar by virtue of its viscoelasticity. The cement substance is thought to be highly compliant or even viscous 22

Table 2 Structural elements of bone

Structural feature	Role in composite structure	Size (µm)	Frequency (MHz) for size = $\lambda/2$
Osteons (human) Laminae (bovine)	Fibre lamina	250	8
Haversian canals	Pore or fluid filled channel	50-150	40-13
Osteocyte lacunae	Pore	10–25	80-200
Lamella	Lamina	5	400
Collagen fibre	Fibre	1-2	2000-1000
Apatite crystals	Particulate inclusion	0.005-0.05	400×10^{3} -40 $\times 10^{3}$

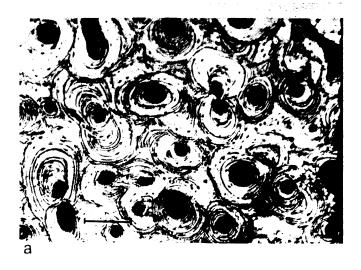




Figure 5 Microstructure of human Haversian bone H.. Reflected light micrograph. a, Cut surface perpendicular to longitudinal direction. b, Radial direction. Scale mark, 0.20 mm

under quasistatic loading, but there is evidence that it is nearly as stiff as the osteon itself at ultrasonic frequencies 23. If that were the case, effects due to the fibrous or laminar architecture of bone might be weak or absent at ultrasonic frequencies.

An additional wave attenuation mechanism may be encountered in materials with interconnected, fluid-filled pores. The dynamics of the fluid-solid interaction are predicted to result in attenuation of acoustic waves 24,25, an attenuation which depends upon the geometry and volume fraction of pores; it can become large in some situations. In the case of wet compact bone, the interconnected, fluid-filled pores are of a much more complex geometry than assumed in the theory. A quantitative comparison, consequently, is not easily achieved.

Relationship to acoustic emission studies

The inverse of the attenuation, α , represents a decay depth: a distance over which the wave amplitude decays to 1/e of its original value. Referring to Figure 4, we observe that over much of the frequency range, longitudinal acoustic waves cannot penetrate more than a millimeter or two without becoming severely attenuated. The

attenuation is particularly large in the case of human bone in the radial direction. Consequently, acoustic emission methods based on signals at or above 0.5 MHz, for detecting microdamage in bone are sensitive only to events occurring near the bone surface. Although the frequency range for acoustic emission may be from zero to 100 MHz, studies on bone have utilized a band from 100 to 300 kHz²⁶. In this latter range a signal would propagate as a kind of Lamb mode of wavelength greater than the bone's cortical thickness. The application to such a situation of our attenuation results for bulk waves may be less than straightforward.

CONCLUSIONS

The following conclusions are drawn from the results of this study.

Ultrasonic waves in wet human and bovine bone exhibit little dispersion of velocity. Consequently the phase, group and signal velocities were virtually identical. The use of wet bone permits different measurement techniques to be employed to obtain comparable values for the ultrasonic velocity.

Large values of ultrasonic attenuation in bone were observed. Attenuation of ultrasonic waves in wet human bone in the radial direction was sufficiently large to limit the penetration depth to 2 mm or less. Techniques based on transmission of highfrequency ultrasonic waves through bone are therefore unlikely to be of use clinically.

No evidence of a cut-off frequency was found. Microstructural resonance at the osteon level, if it occurs at all, does not manifest itself in ultrasonic transmission measurements.

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